

## **HEIDENHAIN**



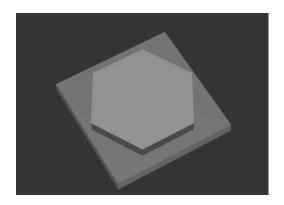
## **NC** solutions

**Description of NC program 2030** 

English (en) 9/2017

## 1 Description of the NC program 2030\_en.h

NC program for creating a regular polygon



## Description

With this NC program, the control machines a regular polygon. You define this polygon by its circumradius.

At program start, you define the tool and all the parameters required for machining.

The control then makes multiple calculations and subsequently begins machining. In the first step, the control pre-positions the tool at the calculated plunging position and at the set-up clearance. Subsequently, the tool moves to the defined milling depth and then to the first corner of the polygon following an arc. In a loop, the control calculates the next corner and approaches it. The control continues to repeat this loop until the specified number of corners has been created. Then the control moves the tool along an arc back to the plunging position.

Finally, the control retracts the tool and ends the NC program.

Parameter	Name	Meaning
Q1	CENTER X-AXIS	Center of the polygon in the X axis
Q2	CENTER Y-AXIS	Center of the polygon in the Y axis
Q3	MILLING DEPTH	Milling depth of the contour
Q4	DIRECTION OF ROTATION	Direction of the milling path +1 for a counterclockwise milling path -1 for a clockwise milling path
Q5	NUMBER OF CORNERS	Number of corners on the polygon
Q6	CIRCUMRADIUS	Radius from the center to the corners of the polygon
Q7	ANGLAR POSITION OF THE FIRST CORNER	Angular position of the corner where machining begins
Q10	SAFETY CLEARANCE	Safe Z position, referenced to the workpiece datum, which the control approaches in rapid traverse
Q11	FEED RATE FOR PLUNGING	Traversing speed of the tool in the Z axis
Q12	FEED RATE FOR MILLING	Traversing speed of the tool in the X/Y plane
Q14	SIDE ALLOWANCE	Oversize in the X/Y plane
Q15	RADIUSCORRECTION	<ul> <li>Direction of the radius compensation</li> <li>0 for a milling path without radius compensation (R0)</li> <li>+1 for a milling path with radius compensation to the left (RL)</li> <li>+2 for a milling path with radius compensation to the right (RR)</li> </ul>

