## HEIDENHAIN



## NC Solutions

Description of NC program 2035

English (en)
8/2017

## 1 Description of the NC program 2035_en.h

NC program for milling a spiral in the $X / Y$ plane

## Description

With this NC program, the control mills a spiral in the $X / Y$ plane The tool move on a path from the inside to the outside. With parameters, you define whether the control:

- Calculates a tool path with tool radius compensation
- Calculates a lateral allowance
- Calculates the tool path in a clockwise or counterclockwise direction

In the first part of the NC program, you define the tool and all the parameters required for the calculation.
After you enter the parameters, the control pre-positions the tool in the center of the spiral and in the $Z$ axis at the defined safety clearance. The control then calls a subprogram. In this subprogram, the control calculates the tool path and traverses this path. The control puts together the milling path from individual points. For each of these points, the control calculates the $X$ and $Y$ coordinates and approaches each point along a linear path. The pitch parameter allows you to define how many points the control calculates along a $360^{\circ}$ path, thereby allowing you to influence the accuracy.
When the tool reaches a point, the control checks the following two possibilities:

- The end radius has not yet been reached: the control repeats the loop with point calculation and path contour
- The end radius has been reached: the tool travels along the $Z$ axis to the set-up clearance
After machining, the control retracts the tool and terminates the program.

| Parameter | Name | Meaning |
| :---: | :---: | :---: |
| Q1 | CENTER X AXIS | $X$ coordinate of the center of the spiral |
| Q2 | CENTER Y AXIS | Y coordinate of the center of the spiral |
| Q3 | DEPTH | Depth of the spiral |
| Q4 | ROTATIONAL DIRECTION | Direction of the milling path <br> - +1 for a counterclockwise milling path <br> - -1 for a clockwise milling path |
| Q5 | PITCH | Number of points calculated on each $360^{\circ}$ path |
| Q6 | START RADIUS | Distance between the center point and the starting point of the spiral |
| 016 | END RADIUS | Distance between the center point and the end point of the spiral |
| Q7 | STARTING ANGLE | Polar angle at the starting point of the spiral |
| Q8 | SLOPE IN MM ON 360 DEGREE | Radius change of the spiral per $360^{\circ}$ revolution |
| Q10 | SET UP CLEARANCE | Safe Z position, referenced to the workpiece datum, which the control approaches in rapid traverse |
| Q11 | FEED RATE FOR PLUNGING | Traversing speed of the tool in the $Z$ axis |
| Q12 | FEED RATE FOR MILLING | Traversing speed of the tool in the $X / Y$ plane |
| 014 | ALLOWANCE FOR SIDE | Allowance in the $X Y$ plane; only takes effect when a radius correction is defined |
| 015 | RADIUS CORRECTION | Correction of the tool radius <br> - 0 for no correction <br> - +1 for outward correction <br> - -1 for inward correction |

Offenders will be held liable for the payment of damages. All rights reserved in the event of the grant of a patent, utility model or design. (ISO 16016 )

| HEIDENHAIN <br> DR. JOHANNES HEIDENHAIN GmbH 83301 Traunreut, Germany | Created | Responsible | Released | Version Revision Sheet | Page <br> 1 <br> of <br> 1 |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Baumgartner |  |  | D1224741-00-A - 1 |  |
|  | 08.08.2017 |  |  | Document number |  |



